

STEREO MOC Status Report
Time Period: 2016:081 - 2016:087

STEREO Ahead (STA) Status:

1. The following Ground System anomalies/events occurred during this reporting period:

- On day 082, during the DSS-43 support, turbo decoder lock was lost intermittently beginning at 0734z. This anomaly resulted in the loss of 466 frames of real-time and SSR data. See DR# N110255 for more information.
- On day 082, the 3rd PN ranging demonstration was conducted during the DSS-26 support. There was no instrument commanding or SSR playback as the DSN track services were not committed. At 083-00:00:49z and 00:01:59z, range measurements were set to zero due to no valid uplink range phase. The new PN ranging system transmits all of the tones at the same time, reducing the cycle time for acquiring range lock, and thus increases the number of range points collected during a support. PN ranging is also easier to use because only one navigation-centric variable is needed: integration time, instead of T1 and T2.
- On day 083, during the DSS-26 support, turbo decoder lock was lost briefly at 2056z. This anomaly resulted in the loss of one frame of SSR data.
- On day 087, during the DSS-26 support, turbo decoder lock was lost briefly at 088-0020z. This anomaly resulted in the loss of one frame of SSR data.

2. The following spacecraft/instrument events occurred during this week. The Ahead observatory operated nominally during this week on the center of the HGA main lobe. The HGA feed assembly was at 109 degrees C and decreasing with the HGA angle at 9.1 degrees and increasing, with respect to the spacecraft-Sun line.

- On day 083, the 86th momentum dump was executed successfully at 2200z, which imparted an estimated delta V of 0.089 m/sec. This was the 5th momentum dump that did not use the IMU. After thruster operations completed, there was a 0.45 degree of roll angle error which was dampened out over the

next 16 minutes. Fine pointing stabilized 2.4 minutes after completion of the momentum dump.

- The average daily science data return for Ahead was 6.0 Gbits during this week.

STEREO Behind (STB) Status:

1. The following Ground System anomalies/events occurred during this reporting period:

- None as recovery tracks are every other week.

2. Detailed status of the recovery activities to restore operations from the Behind loss of communication anomaly, which occurred on October 1, 2014, are listed below.

- The Behind observatory entered superior solar conjunction at the 2.0 degree SPE angle on January 22, 2015. Recovery efforts resumed post solar conjunction on May 4th through June 27, 2015, as the spacecraft had cleared solar interference for LGA communications. The Failure Review Board recommendations were implemented consisting of battery state of charge recovery and powering on the downlink carrier. The Green Bank Radio Telescope and the Arecibo Observatory also observed the carrier recovery tracks. No downlink signal has been detected. Due to Behind's retrograde motion causing it to re-enter the region of solar interference, recovery operations were suspended from June 28th through November 29, 2015. Weekly recovery operations resumed on November 30, 2015. The Green Bank Radio Telescope and the Allen Telescope Array will also observe the carrier recovery tracks depending on availability. While the Arecibo Observatory is willing also assist, the Behind observatory is not in view until April 2016. Recovery operations were reduced to every other week beginning on March 21st to minimize the impact on DSN resources.
- The Failure Review Board's recommended faster frequency segmented acquisition sequence was tested with the Ahead observatory on September 29, 2015. All 18 one kHz frequency steps were tested twice. While stepping down through the 1 kHz segments, on segment #9 going down in frequency, the transponder locked to the BLF and accepted 9 no-op commands as expected. An interesting finding, but

not unexpected, was that the transponder continued to follow the moving carrier and accept all commands sent for the remaining 27 segments.

- As commands must be received to recover the Behind observatory, the first use of the newly developed DSN uplink arraying capability for Behind recovery operations occurred on March 17th. The uplink array capability will provide four times the uplink received power as a 70m station. The uplink array consists of using an 80 kW and two 20 kW transmitters from three 34m Goldstone stations, DSS-24, 25, and 26, with each uplink being precisely phase shifted to create a constructive interference. From testing with STEREO Ahead, an approximate 12 dBm increase in received uplink power, as compared to a single 34m, has been successfully demonstrated each time. As the Behind observatory may be rotating, a frequency segmented acquisition sequence will be used with the uplink array. For each use of the uplink array, as transponder feedback is required, the Ahead observatory is first used to calibrate the phased uplink array then the three stations are switched to point to the Behind observatory sending commands for recovery. The uplink array will be used twice monthly within a three day period, once for battery recovery and again for carrier recovery.
- As time goes by, the ephemeris error increases degrading DSN antenna pointing. However, with time the spacecraft range also decreases improving RF communications and the ability for other assets to acquire data on Behind. Analysis indicates that the total RF gain change is significant and the probability of command success increases with time.

Significant findings to date:

1. Analysis of the three DSN extracted telemetry frames from the carrier signal just before the planned observatory reset/anomaly occurred on October 1, 2014 showed nominal performance of the spacecraft, i.e., no anomalies, IMU off, and the star tracker providing an attitude solution.
2. Post reset, from the very limited telemetry, three packets, extracted from the carrier signal by the DSN, the X-axis gyro on IMU-A had failed. Unfortunately, this telemetry contained only G&C anomaly data and no spacecraft summary data, i.e., the state of the RF, G&C, fault protection and

other subsystems is not known at the time of the anomaly. With a failed IMU and the star tracker being off-line for an undetermined duration, the sun sensors will keep the observatory pointed at the Sun, though the G&C will not have any roll knowledge, and cannot roll the observatory as part of the safing configuration to re-establish communications on the LGAs. From analysis of this telemetry and initial G&C simulations, it is highly suspected that the observatory is rotating about the principal axis of inertia due to an autonomous momentum dump initiated by highly biased gyro data flagged good by the IMU, but this has not yet been confirmed.

3. At least two anomalies occurred post reset, the star tracker not promoting to AAD mode and the X-axis gyro failure. Unfortunately, due to the number of possible combinations, the STEREO fault protection system is not designed for simultaneous failures.

Once communications are restored and the anomaly resolved, the Behind observatory will be returned to nominal science data collection as soon as it is safely possible.